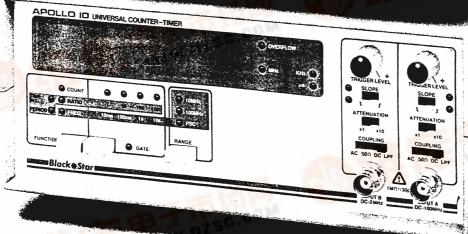
APOLLO Series

of universal counter-timers and the APOLLO 'X' Series with TCXO





● DC - 100MHz range

.dzsc.com

- Frequency, single & average period, count, ratio, time interval, stop-watch, RPM
- Trigger level and slope controls
- x1/x10 input attenuators
- Reset and display hold controls

- Switchable low-pass filter
- Frequency multiplier
- Resolution down to 0.001Hz
- External timebase facility
- 8 digit LED display
- Mains operated
- 1 year guarantee



680 461

Designed and manufactured in Britain



The Apollo series of **查询"A100Umiversal counter-timers**

Apollo 10X | Apollo 100 | Apollo 100X

SPECIFICATION

	Apollo 10	Apollo 10X	Apollo 100	Apolio 100X		
Timebase						
Crystal oscillator						
frequency	10MHz					
Time between	200ms nom. Adjustable 200ms to 10 sec					
measurements			nom. (Ho	ld control)		
Aging	<±5ppm/year	<±1ppm/year	<±5ppm/year	<±1ppm/year		
Setability	<±0.5ppm	<±0.2ppm	<±0.5ppm	<±0.2ppm		
Temperature	±10ppm	<± 1ppm	<±10ppm	<±1ppm		
setability	-10°C to +70°C	0°C to 50°C	-10°C to +70°C	0°C to 50°C		
Input A	10MHz range < 5mV DC – 10MHz					
Bandwidth/ Sensitivity	100MHz range <10mV 1MHz - 50MHz <30mV 50MHz - 100MHz					
Coupling & input impedance	DC @ 1MΩ//30pF; AC @ 1MΩ//30pF; 50Ω					
Low pass filter			50kHz nom; swit			
Maximum input voltage			V rms @ 50Hz de C coupling: 300V			
Triggering			ge; LEDs indicate			
Attenuator	Lever adjustable	x1, x10 s		when triggered		
Input B						
Bandwidth/		<5mV DC - 2 M	1Hz			
Sensitivity Coupling & input						
impedance	DC @ :	1MΩ//30pF; AC	@ 1MΩ//30pF;	50Ω		
Low pass filter	Coupling DC	cut-off frequent	cy 50kHz: switch	selectable		
Maximum input	AC coupling:	50V DC or 250	V rms @ 50Hz de	creasing to		
voltage	5V rn	ns @ >70kHz; D	C coupling: 300V	DC DC		
Triggering	Level adjustable,	+ ve or - ve ed	ge; LEDs indicate	when triggered		
Attenuator		x1, x10 s				
Frequency A						
Gatetimes	(0.01 sec: 0.1 se	ec; 1 sec; 10sec			
	· · · · · · · · · · · · · · · · · · ·		Multiplier			
Ranges/ resolution		OC – 10MHz (1 Hz – 100MHz (6Hz –10kHz (0.01 Multiplier 14Hz –100kHz (0.1 . ÷ gate time) Hz (10 ÷ gate time) H PSC (100 ÷ ga	1÷ gate time) Hz † Hz		
			PSC (100 ÷ ga	ite time) nz		
Accuracy	PSC ÷ 100 (100 ÷			ite tille) nz		
	PSC ÷ 100 (100 ÷	gate time) Hz		ite time) nz		
Frequency ra	PSC ÷ 100 (100 ÷ ±	gate time) Hz	base accuracy)	te time) nz		
Frequency ra Frequency maximum Ratio averaged	PSC ÷ 100 (100 ÷ ± atio A to B	gate time) Hz (1 count + time Input A: 10MHz;	base accuracy) Input B:2 MHz			
Frequency ra Frequency maximum Ratio averaged over	PSC ÷ 100 (100 ÷ ± atio A to B	gate time) Hz (1 count + time Input A: 10MHz;	base accuracy) Input B:2 MHz cycles of input B			
Frequency ra Frequency maximum Ratio averaged over Resolution	PSC ÷ 100 (100 ÷ ± atio A to B	gate time) Hz (1 count + time) Input A: 10MHz; 10, 100, 1000 1 ÷ no. of cycl	base accuracy) Input B:2 MHz cycles of input B es of input B			
Frequency ra Frequency maximum Ratio averaged over Resolution Accuracy	PSC ÷ 100 (100 ÷ ± atio A to B	gate time) Hz (1 count + time Input A: 10MHz;	base accuracy) Input B:2 MHz cycles of input B es of input B			
Frequency ra Frequency maximum Ratio averaged over Resolution Accuracy	PSC ÷ 100 (100 ÷ ± atio A to B	gate time) Hz (1 count + time) Input A: 10MHz; 10, 100, 1000 1 ÷ no. of cycl	base accuracy) Input B:2 MHz cycles of input B es of input B			
Frequency ra Frequency maximum Ratio averaged over Resolution Accuracy Period A	PSC ÷ 100 (100 ÷ ± atio A to B	gate time) Hz (1 count + time) Input A: 10MHz; 10, 100, 1000 1 ÷ no. of cycl ± 1 c	Input B:2 MHz cycles of input B es of input B ount			
Frequency ra Frequency maximum Ratio averaged over Resolution Accuracy Period A Measurement type	PSC ÷ 100 (100 ÷ ± atio A to B	gate time) Hz (1 count + time) Input A: 10MHz; 10, 100, 1000 1 ÷ no. of cycl ± 1 c	Input B:2 MHz cycles of input B es of input B ount			
Accuracy Frequency ra Frequency maximum Ratio averaged over Resolution Accuracy Period A Measurement type Period range	PSC ÷ 100 (100 ÷ ± atio A to B	gate time) Hz (1 count + time) Input A: 10MHz; 10, 100, 1000 1 ÷ no. of cycl ± 1 c cycle and multip	Input B:2 MHz cycles of input B es of input B ount le period average 10 sec			
Frequency ra Frequency maximum Ratio averaged over Resolution Accuracy Period A Measurement type Period range Display Period averaged	PSC ÷ 100 (100 ÷ ± atio A to B	gate time) Hz (1 count + time) Input A: 10MHz; 10, 100, 1000 1 ÷ no. of cycl ± 1 c. cycle and multip 500ns –	Input B:2 MHz cycles of input B es of input B ount le period average 10 sec			
Frequency ra Frequency maximum Ratio averaged Over Resolution Accuracy Period A Measurement type Period range Display Period averaged Over	PSC ÷ 100 (100 ÷ ± atio A to B	gate time) Hz (1 count + time) Input A: 10MHz; 10, 100, 1000 1 ÷ no. of cycl ± 1 c cycle and multip 500ns – µs 1, 10, 100, 1	Input B:2 MHz cycles of input B es of input B ount le period average 10 sec			
Frequency ra Frequency maximum Ratio averaged over Resolution Accuracy Period A Measurement type Period range Display Period averaged over Resolution	PSC ÷ 100 (100 ÷ ± atio A to B	gate time) Hz (1 count + time) Input A: 10MHz; 10, 100, 1000 1 ÷ no. of cycl ± 1 c cycle and multip 500ns - µs 1, 10, 100, 1	Input B:2 MHz cycles of input B es of input B ount le period average 10 sec			
Frequency ra Frequency maximum Ratio averaged Over Resolution Accuracy Period A Measurement type Period range Display Period averaged Over	PSC ÷ 100 (100 ÷ ± t) atio A to B 1, Single	gate time) Hz (1 count + time) (2 count + time) (2 count + time) (3 count + time) (4 count + time) (5 count + time) (6 count + time) (6 count + time) (7 count	Input B:2 MHz cycles of input B es of input B ount le period average 10 sec 6 1000 cycles cycles averaged cy + resolution +			
Frequency ra Frequency maximum Ratio averaged over Resolution Accuracy Period A Measurement type Period range Display Period averaged over Resolution Accuracy	PSC ÷ 100 (100 ÷ ± t in the state of the sta	gate time) Hz (1 count + time) (2 count + time) (2 count + time) (3 count + time) (4 count + time) (5 count + time) (6 count + time) (6 count + time) (7 count	Input B:2 MHz cycles of input B es of input B ount le period average 10 sec			
Frequency ra Frequency maximum Ratio averaged Over Resolution Accuracy Period A Measurement type Period range Display Period averaged Over Resolution Accuracy Items interva	PSC ÷ 100 (100 ÷ ± t in the state of the sta	gate time) Hz (1 count + time) (2 cycle and multiput for the cycle and multiput f	Input B:2 MHz cycles of input B es of input B ount ble period average 10 sec 6 1000 cycles cycles averaged cy + resolution + f cycles averaged			
Frequency ra Frequency maximum Ratio averaged over Resolution Accuracy Period A Measurement type Period range Display Period averaged over Resolution Accuracy	PSC ÷ 100 (100 ÷ ± t in the state of the sta	gate time) Hz (1 count + time) (2 cycle and multiple for the cycle and multiple f	Input B:2 MHz cycles of input B es of input B ount le period average 10 sec 1000 cycles cycles averaged acy + resolution + f cycles averagec			
Frequency ra Frequency ra Frequency maximum Ratio averaged over Resolution Accuracy Period A Measurement type Period range Display Period averaged over Resolution Accuracy Time interva Range Display	PSC ÷ 100 (100 ÷ ± t in the state of the sta	gate time) Hz (1 count + time) (2 cycle and multiput for the cycle and multiput f	Input B:2 MHz cycles of input B es of input B ount le period average 10 sec 1000 cycles cycles averaged acy + resolution + f cycles averagec			
Frequency ra Frequency ra Frequency maximum Ratio averaged over Resolution Accuracy Period A Measurement type Period range Display Period averaged over Resolution Accuracy Fime interva Range Display Joinsplay Join	PSC ÷ 100 (100 ÷ ± t in the state of the sta	gate time) Hz (1 count + time) (2 cycle and multiput for the cycle and multiput f	Input B:2 MHz cycles of input B es of input B ount ble period average 10 sec 1000 cycles cycles averaged acy + resolution + f cycles averaged			
Frequency ra Frequency ra Frequency maximum Ratio averaged Over Resolution Accuracy Period A Measurement type Period range Display Period averaged Over Resolution Accuracy Frequency F	PSC ÷ 100 (100 ÷ ± t in the state of the sta	gate time) Hz (1 count + time) (2 cycle and multiput for the count in th	Input B:2 MHz cycles of input B es of input B ount ble period average 10 sec 10000 cycles cycles averaged cycles averaged cycles averaged 10 sec			
Frequency ra Frequency raximum Ratio averaged Over Resolution Accuracy Period A Measurement type Period range Display Period averaged Over Resolution Accuracy Time interva Range Display Minimum pulse Maximum frequency	PSC ÷ 100 (100 ÷ ± t in the state of the sta	gate time) Hz (1 count + time) (2 cycle and multiput for the cycle and multiput f	Input B:2 MHz cycles of input B es of input B ount ble period average 10 sec 10000 cycles cycles averaged cycles averaged cycles averaged 10 sec			
Frequency ra Frequency maximum Ratio averaged over Resolution Accuracy Period A Measurement type Period range Display Period averaged over Resolution Accuracy Fime interva Range Display Inimum pulse width Maximum frequency Ime interval	PSC ÷ 100 (100 ÷ ± t in the state of the sta	gate time) Hz (1 count + time) (2 cycle and multiperson - time) (3 cycle and multiperson - time) (4 cycle and multiperson - time) (5 cycle and multiperson - time) (6 cycle and multiperson - time) (7 cycle and multiperson - time) (8 cycle and multiperson - time) (9 cycle and multiperson - time) (1 cycle and multiperson - time) (1 cycle and multiperson - time) (1 cycle and multiperson - time) (2 cycle and multiperson - time) (2 cycle and multiperson - time) (2 cycle and multiperson - time) (3 cycle and multiperson - time) (4 cycle and multiperson - time) (5 cycle and multiperson - time) (6 cycle and multiperson - time) (7 cycle and multiperson - time) (8 cycle and multiperson - time) (8 cycle and multiperson - time) (9 cycle and multiperson - time)	Input B:2 MHz cycles of input B es of input B ount ble period average 10 sec 6 1000 cycles cycles averaged acy + resolution + f cycles averaged 10sec 10sec			
Frequency ra Frequency maximum Ratio averaged over Resolution Accuracy Period A Measurement type Period range Display Period averaged over Resolution Accuracy Fime interva Range Display Minimum pulse width Maximum frequency ime interval veraged over	PSC ÷ 100 (100 ÷ ± atio A to B 1, Single ± t([trigg	gate time) Hz (1 count + time (1 count + time) Hz (1 count + time)	Input B:2 MHz cycles of input B es of input B ount ble period average 10 sec 1000 cycles cycles averaged acy + resolution + ff cycles averaged 10sec			
Frequency ra Frequency maximum Ratio averaged over Resolution Accuracy Period A Measurement type Period range Display Period averaged over Resolution	PSC ÷ 100 (100 ÷ ± atio A to B 1, Single ± ([trigg	gate time) Hz (1 count + t	Input B:2 MHz cycles of input B es of input B ount ble period average 10 sec 1000 cycles cycles averaged acy + resolution + ff cycles averaged 10sec			

	Apollo 10 Apollo 10X	Apollo 100	Apollo 100X			
Count A						
Count maximum	10*-1					
Input frequency		MHz max.				
Resolution	1 count					
Reset	External reset input		set button) or			
		external	reset input			
Gating	Input B	/start button)I				
		or Ir	put B			
Stopwatch		ļ				
Display	1	80	oondo			
Times to			conds (>11 days)			
Resolution	1		Oms			
Accuracy	1		ccuracy + 10ms			
Reset	1		eset button)			
]		I reset input			
Gating		Manual (sto	p/start button)			
	4	or ii	nput B			
RPM A						
Display	1	1000	Yo DDM			
Range	1		0's RPM			
Gate time	1		ec: 6 sec: 60 se			
Resolution	1		e time) RPM			
Accuracy	1		curacy + 1 cour			
External time!						
External timel	Dase External of	oscillator in/intern	al			
oscillator	oscillator out; switch					
Calibration frequency		10MHz				
nput frequency range	100kHz n	om. min. to 10MH.	z			
nput voltage range		ΠL				
nput load	1 +	HCMOS input				
Output frequency		10MHz				
Output drive	Sink 5	mA, source 5mA				
External						
reset input	Active low; TTL compatible;	input voltado rando	+ 201/			
occi iiipat	Active low, TTE compatible,	input voitage range	E I ZUV Max.			
Power						
requirements	Mains operation only. 10		240V AC			
equil ements	50 - 60	OHz; 24VA				
Displays	9 Digit 7 cogmont 0 5" brish	A 1 FD				
Jiopiuy 3	8 Digit 7-segment 0.5" bright LEDs; automatic decimal point; leading zero suppression. Unit indicators for MHz, kHz, sec,					
	µsec, KRPM; overflow	v indicator; gate in	dicators			
Anaillanı						
Ancillary		Display hold: ad	diustable			
ontrols		200ms to 10 s				
Front panel)		Trigger hold-off:				
		5 to 500ms no				
		Single measure Start/stop and				
Conorol						
General						
nvironmental						
perating range	0°C to + 40°C (10% -	80% RH non-cond	ensing)			
ase	Robust, lightweight steel painted light grey with tilt stand					
ize	212mm x 228mm x 100mm (product only)					
la: ala	318mm x 356mn	n x 141mm (packe	d)			
/eight upplied accessories		nly) 3.3 Kg (packe				
COURT ACCESSORES	Mains lead, instruction manual, spare fuse					
	Passive probes, service manual					
ptional accessories	Dower on Joffs on f.	ICO: Outor!	:			
ptional accessories ear panel facilities	Power on/off; spare fu	use; external reset	input;			
ptional accessories	Power on/off; spare for external timebase; Complies to EN500	internal timebase	out			

Black Star reserve the right to alter specifications without notice

Designed and manufactured by



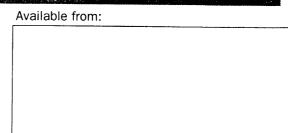
BLACK STAR LIMITED

4 Harding Way, St. Ives, Huntingdon, Cambridgeshire PE17 4WR England

Telephone: 01480 462440 Fax: 01480 495172



Designed and manufactured in Britain



SPECIFICATION

查询"A100"供应**商LLO 10** APOLLO 10X APOLLO 100 APOLLO 100X TIMEBASE Crystal Oscillator Frequency 10MHz 10MHz 10MHz 10MHz Time Between Measurements 200ms nom 200ms nom Adjustable 200ms to 10s nom (hold control) < ±5ppm/year < ± 1ppm/year < ±5ppm/year < ± lpptn/year Setability < ±0.5ppm < ±0.2ppm $< \pm 0.5$ ppm < ±0.2ppm Temperature Stability ±10ppm -10-+70°C < ± 1ppm 0-50°C ±10ppm -10-+70°C < ± 1ppm 0-50°C INPUT A 10MHz Range <5mV DC - 10MHz Bandwidth/Sensitivity 100MHz Range: <10mV 1MHz - 50MHz, <30mV 50MHz - 100MHz Coupling and Input Impedance DC @ 1M0//30pF; AC @ 1M0/30pF;500 Low Pass Filter DC coupled, cut off frequency 50kHz nom, switch selectable Maximum Input Voltage AC Coupling: 50V DC or 250V mms @ 50Hz decreasing to 5V mms @ >70kHz, DC coupling: 300VDC Triggering Level adjustable, +ve or -ve edge; L.E.D's indicate when triggered Attenuator X1, X10 Switchable INPUT B Bandwidth/Sensitivity <5mV DC - 2MHz Coupling and Input Impedance DC @ 1MΩ//30pF; AC @ 1MΩ/30pF;50Ω Low Pass Filter DC coupled, cut off frequency 50kHz nom switch selectable Maximum Input Voltage AC Coupling: 50V DC or 250V rms @ 50Hz decreasing to 5V rms @ >70kHz, DC coupling: 300VDC Triggering Level adjustable, +vc or -ve edge; L.E.D's indicate when triggered Attenuator X1, X10 Switchable Note. Input A and Input B Sensitivity figures are r.m.s values for a sine wave input. For frequencies of 100kHz and below the LPF (Low Pass Filter) should be used. FREQUENCY A Gate Times 0.01s,0.1s,1s,10s Ranges/Resolution N/A N/A Multiplier 14Hz-10kHz (0.01 + Gatt time) Hz# 6Hz-100kHz (0.1 ÷ Gate time) Hz+ DC-10MHz (1 + Gate time), 1MHz-100MHz (10 + Gate time) PSC (100 + Gate time) Hz PSC + 100 (100+ Gate time) Hz N/A N/A Accuracy ±(1count + timebase accuracy) FREQUENCY RATIO A TO B Maximum Frequency Input A:10MHz: Input B:2MHz Ratio Averaged over 1,10,100,1000 cycles of input B Resolution 1 + n.o of cycles of input B Accuracy ±1 count PERIOD A Measurement Type Single cycle and multiple period average Period Range 500as - 10 seconds Display Period Averaged Over 1,10,100,1000 cycles Resolution 100ns + n.o of cycles averaged Accuracy ±(timebase accuracy + resolution + (trigger error* + n.o of cycles averaged)) TIME INTERVAL A TO B Range 250ns - 10 seconds Display μS Minimum Pulse Width 250ns Maximum Frequency 2MHz Time Interval Averaged over 1,10,100,100 incervals Acsolution 100ns + n.o of intervals averaged Accuracy ±(timebase accuracy + resolution + (trigger error* + n.o of intervals averaged)) COUNT A Count Maximum 108-1 104-1 108-1 105.1

IOMHz

10MHz

10MHz

Input Frequency

10MHz

Resolution	1 Count	1 Count	1 Count	1 Cougt
Reset	Ext. Reset	Ext. Reset	Manual Reset or Ext. Reset input	
Gating	Input B	Input B	Manual (stop/start button) or input B	
STOPWATCH				
Display	N/A	N/A	Seconds	
Times To	N/A	N/A	106 sec (>11 days)	
Resolution	N/A	N/A	10ms	
Accuracy	N/A	N/A	±timebase accuracy + 10ms	
Reset	N/A	N/A	Manual (reset button) or External reset input	
Gating	N/A	N/A	Manual (scart/stop) or input B	
RPM A				
Display	N/A	N/A	1000's RPM	1000's RPM
Range	N/A	N/A	1 to 1011 RPM	1 to 10 ¹¹ RPM
Gate Time	N/A	N/A	0.06sec; 0.6sec; 6sec; 60sec	
Resolution	N/A	N/A	(60 ÷ gate time) RPM	
Accuracy	N/A	N/A	±(timebase accuracy + 1 count)	
EXTERNAL TIMEBASE	E OSCILLATOR	External oscillator in/in	ternal oscillator out, switch selec	table TTL comparible
Calibration Frequency	10MHz	i0MHz	10MHz	10MHz
Input Frequency Range		100kHz nominal minimum		
Input Voltage Range	0-5 V Max	0-5V Max	0-5V Max	0-5V Max
Input Load	I HCmos input	l HCmos input	1 HCmos input	1 HCmos input
Output Frequency	10MHz	10MHz	10MHz	10MHz

EXTERNAL RESET INPUT POWER REQUIREMENTS

Active low; TTL compatible; input voltage range ±20V max Mains Operation only, 100-120V, 220-240V AC 50-60Hz; 24VA

Sink 5mA, source 5mA

DISPLAYS

8 Digit 7 segment 0.5' bright L.E.D's; automatic d.p; leading zero suppression unit indicators for MHz. kHz. sec. usec, kRPM, overflow and gate indicators.

ANCILLARY CONTROLS N/A

N/A

Display hold:adjustable 200ms-10s Trigger hold:adjustable 5 - 500ms Single measurement.

Start/Stop & Reset

GENERAL

Output Drive

Environmental Operating Range

Indoor use only

Altitude:

Installation category:

Pollution degree:

Insulation Rating:

Case

Size

Weight

Supplied Accessories

Optional Accessories

Rear Panel Facilities EMC

 0° C to + 40° C (10% - 80% RH non condensing)

up to 2000m

2

1

Custom made, sturdy, metal case, with tilt stand

215 X 230 X 98mm (Product only), 321 X 352 X 174mm (Packed)

2.7kg (product), 3.6kg (packed)

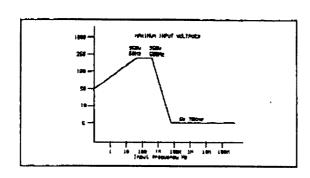
Mains lead, instruction manual, spare fusc

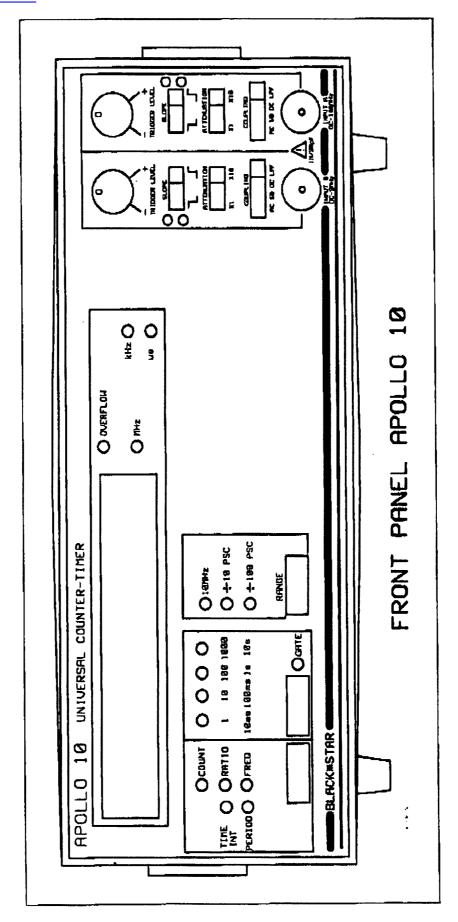
Passive probes, BNC cable assemblies, Service manual

Power On/Off, Spare fuse, external reset input, external timebase, int. timebase out

Complies with EN50081-1 and EN50082-1

*Typical trigger error = 1.6 / (slope / (V/ μ s)) # Typically 5sec settling time





INSTALLATION

The following CAUTION symbol appears on the instrument. Please refer to the appropriate section of this manual before making any adjustments or external connections to the instrument.



Safety Instructions.

The Apollo has been designed to comply with EN 61010-1 safety requirements. When the instrument is connected to the mains voltage supply, in order to maintain safe operation it must be earthed, via the earth connection using a suitable 3 core mains lead. While connected to the mains potentially lethal voltages are present inside the case. Therefore before opening the case disconnect the mains supply by removing the mains cable from the rear panel socket

Front Panel Controls

Function Pushbutton

Sets the counter to the desired measurement function. LED indicators illuminate to indicate the selected function.

Freq (A)

Sets the counter to measure the frequency of the signal connected to input A.

Ratio (A/B)

Sets the counter to measure the frequency ratio A/B of the signals connected to input A and B.

Count (A)

Sets the counter to totalize the number of selected signal edges appearing at input A. The count may be gated by input B or controlled by the START/STOP button (Apollo 100). The counter is reset to zero by the front panel reset button (Apollo 100) or the rear panel reset input.

Time Int (A-B)

Sets the counter to measure the time interval between the selected signal edge at input A and the selected signal edge at input R

Period (A)

Sets the counter to measure the period time of a repetitive signal applied to input A.

Stopwatch (Apollo 100)

Sets the counter to the stopwarch mode of operation. The stopwarch is controlled by the start/stop button or alternatively by a gating signal applied to input B. The counter is reset by either the front panel or the rear panel external RESET input.

RPM (Apollo 100)

Sets the counter to preform a revolution per minute measurement of the signal applied to input A.

Gate

- (i) Sets the gate time of the internal counter circuitry for frequency and RPM measurements.
- (ii) Selects the number of signal cycles over which the signal is averaged for TIME INT, PERIOD and RATIO functions.

Range Pushbutton

Sets the counter to the desired frequency range when performing frequency measurements. Indicator LED's illuminate to show the selected range.



Sets the counter to measure frequency to a maximum of 10MHz.

100MHz (Apollo 100)

Sets the counter to measure frequency to a maximum of 100MHz.

Prescaler (Apollo 100)

The prescaler position provides correct decimal point positioning when using the counter with and external ÷ 10 prescaler to extend frequency measurement to 1GHz.

÷10 (Apollo 10)

Provides correct decimal point positioning when using an external prescaler to extend measurement to 100MHz.

÷100 (Apollo 10)

Provides correct decimal point positioning when using an external prescaler to extend measurement to 1GHz.

Multiplier 10kHz (Apollo 100)

Provides a 100-fold increase in resolution when making frequency measurements between 14Hz and 10kHz.

Multiplier 100kHz (Apollo 100)

Provides a 10-fold increase in resolution when making frequency measurements between 6Hz and 100kHz.

Lock Led (Apollo 100)

Indicates the status of the multiplier circuitry. Blinking = multiplier action in progress. ON = display valid.

Single Measure (Apollo 100)

When depressed sets the counter to single time interval measurements. In this mode the counter performs a single time interval measurement between a signal edge at input A and a signal edge at input B. N.B Before performing a single time interval measurement the counter must be "primed" (see operating instructions section).

Start/Stop (Apollo 100)

The START/STOP button controls the counter in the stopwatch and count modes of operation and is used in the priming procedure when making single time interval measurements.

Reset (Apollo 100)

Reset the counter when pressed, halting any measurement in progress, returns the display to zero and prepares the counter for the next measurement.

Hold (Apollo 100)

Pressing the HOLD pushbutton illuminates the HOLD LED and causes the counter to hold the display at the last measurement made.

Variable Hold Control (Apollo 100)

With the HOLD button released the variable control sets the delay time between the end of one measurement and the start of the reset, during which the display holds the result of the last measurement. Adjustable from 200ms to 10sec.

Hold-Off (Apollo 100)

With the hold off button depressed the counter ignores all input B events during the set hold-off time. The hold-off time is adjustable from 5ms to 500ms. Normal operation resumes when the button is released.

INPUT AMPLIFIERS

Trigger Level

The trigger level control provides a variable trigger level of nominally ± 200 mV. When the X10 attenuator is selected the effective trigger level becomes ± 2 V.

Slope

When set to the +VE position, triggering occurs as the positive going edge of the input waveform and when set to the -VE position, triggering occurs on the negative going edge of the input waveform.

Attenuation

When set to the X10 position the sensitivity of the input amplifiers is decreased by a factor of 10 and the effective trigger level becomes $\pm 2V$.

Coupling

- A.C blocks the D.C component of the input signal. The lower 3dB frequency when AC coupled is $\approx 0.7 Hz$. Input impedance is nominally $1M\Omega//30pF$.
- D.C The input signal is directly coupled to the input amplifier. The input impedance is nominally IMQ//30pF.
- L.P.F (low pass filter) The input signal passes through a 50kHz low pass filter which improves the triggering of noisy low frequency signals. The input is DC coupled and the input impedance is nominally $1M\Omega//30pF$.
- 50Ω This terminates the input signal with a nominal impedance of 50Ω . The input circuitry comprises a series combination of a 6n8 capacitor and a 51Ω resistor giving a lower 3dB frequency of $\approx 460 \text{kHz}$

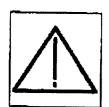
Rear Panel



The caution symbols appears on the rear panel of the instrument. To ensure safe operation, no adjustment of the tamper proof earth bond point should be made.

Off...On

Supplies mains power to the counter in the '1' position and switches the counter off in the 'O' position. The switch has a double pole action.



Reset

This input has the same function as the front panel RESET button. The input is active low and is TTL compatible.

Ref. Osc

With the switch in the INT O/P position the internal 10MHz reference signal is available on the adjacent BNC connector. With the switch in the EXT I/P position the BNC connector becomes the input for external reference signal.

Power Socket and Fuse

The power socket is the 3 pin I.E.C type with the integral fuse holder and spare fuse compartment. The fuse is a 20mm 250mA anti-surge.

If the mains fuse requires replacement then the following type must be used. Fitting any other type will invalidate the Guarantee and may make the instrument unsafe.

at input B.

5. The counter will now time and display the result of the time interval between a start event at input A and a stop event at input B.

Time Interval Average

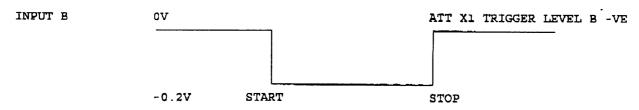
- 1. Select TIME INT function.
- 2. Select TRIGGER LEVEL B, COUPLING, SLOPE and ATTENUATION to suit signals being measured.
- 3. Select number of cycles over which measurement is to be averaged to give optimum resolution and measurement time.

Count (when using Apollo 100)

- 1. Select COUNT mode.
- 2. Set TRIGGER LEVEL fully anticlockwise.
- 3. Select TRIGGER LEVEL, COUPLING, SLOPE and ATTENUATION to suit signals being counted.
- 4. To initiate count press START/STOP button.
- 5. To stop count press START/STOP button again.
- 6. The total count is held on the display until a RESET is initiated or another counter function is selected.

Count A Gated by B (Apollo 10 or 100)

In this mode the counter totalizes the number of selected signal edges appearing at input A during the time interval between the leading and trailing edges of a negative going gating signal applied to input B.



- 1. Select COUNT mode.
- 2. Select TRIGGER LEVEL (A). COUPLING (A), SLOPE (A) and ATTENUATION (A) to suit signals being counted.
- 3. Select TRIGGER LEVEL (B), and ATTENUATION (B) to suit gating signal.
- 4. Set coupling (B) to DC or LPF.
- 5. Connect signal to be counted to input A.
- 6. Connect gating signal to input B. The counter is reset to zero by initiating a RESET or by selecting another counter function.

Stopwatch (Apollo 100)

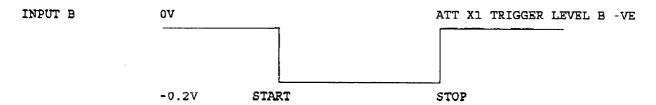
- Select STOPWATCH function.
- 2. Set TRIGGER LEVEL B fully anticlockwise.
- 3. Press START/STOP button to start timing.
- 4. Press START/STOP to stop timing.
- 5. Displayed time is held until stopwatch is restarted by pressing START/STOP button, timing then commences from last displayed value.
- 6. The stopwatch is reset to zero by initiating a RESET.
- 7. The HOLD pushbutton provides a lap timer function when used in conjunction with the stopwatch. When depressed the displayed time is held, but the internal timing continues. When the HOLD button is released the display updates to the internal timing and the stopwatch continues.

Stopwatch Gated By B (Apollo 100)

Apart from the manual operation of the stopwatch using the START/STOP button, the stopwatch can also be controlled by and externally applied gating signal applied to input B.

- 1. Select STOPWATCH function.
- 2. Select TRIGGER LEVEL (B), and ATTENUATION to suit gating signal.

- 3. Set COUPLING (B) to DC or LPF.
- Connect gating signal to input B.



Frequency Ratio A/B

- 1. Select the RATIO function.
- 2. Select required GATE time for optimum resolution and measurement time.
- 3. Select input A and B COUPLING and ATTENUATION to suit signals to be measured.
- 4. Connect higher frequency to input A and lower frequency to input B.
- 5. Adjust TRIGGER LEVEL controls until trigger LED's are illuminated and a stable reading is obtained.

R.P.M (Apollo 100)

The counter performs a revolutions per minute measurement on the signal connected to input A. The result is displayed as KRPM, (thousands of revolutions per minute), provided that the transducer used gives only one pulse output per revolution. The internal counter circuitry performs the RPM measurement in the same way as the frequency measurement, except that the gate time is six times that of the frequency measurement.

The setting up procedure is as for frequency measurement. The maximum available resolution in the RPM mode is 1 RPM when using a 60 second gate time. In some circumstances a long gate time may be unacceptable, in which case it is preferable to make a frequency measurement and then convert measured frequency to RPM using the formula: RPM = (Frequency X 60) / n

Where n = number of transducer pulses per revolution.

Application Examples

1. Frequency ratio

The frequency ratio mode of measurement can be especially useful when calibrating an oscillator to and awkward frequency, say for example a frequency of 1.784MHz. The procedure is to connect the reference signal to input A and the oscillator to be calibrated to input B. The oscillator is then adjusted until the counter reads 1.000, which is much easier to read than 1.784MHz.

2. Velocity Measurements

One of the many practical uses of the counter is velocity measurement of a travelling object. The diagram outlines the arrangement needed to measure the speed of a vehicle.

Using the counters TIME INT function the speed of the vehicle is calculated from the formula: Speed = d/t. Where d = the distance travelled and t = the measured time interval. Note due to the many and varied types of photo detectors available some form of signal conditioning circuit may be necessary to interface to these devices to the counter.

